

Mathematical modeling of maximum height of roughness profile in turning with using wiper insert geometry

Matematyczne modelowanie maksymalnej wysokości profilu chropowatości po toczeniu ostrzami z geometrią wiper

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This paper presents mathematical models for predicting the maximum height of roughness profile using a wiper insert. Identified are four characteristic cases that occur turning when used wiper insert geometry as a function of the feed f . It also notes several inconsistencies and differences regarding the definition of wiper insert geometry.

KEYWORDS: mathematical modeling, wiper insert geometry, turning, roughness profile.

Przedstawiono modele matematyczne do prognozowania maksymalnej wysokości profilu chropowatości podczas skrawania ostrzami typu Wiper. Zidentyfikowano cztery przypadki, które pojawiają się podczas kształtowania tymi ostrzami w zależności od wartości posuwu f . Zwrócono uwagę na pewne niejasności i różnice w definiowaniu geometrii wiper.

SŁOWA KLUCZOWE: modelowanie matematyczne, geometria Wiper, toczenie, profil chropowatości.

A lot of research exists [1-6] aiming at predicting and analyzing the surface roughness obtained using wiper insert geometry. Analyzing the geometric interpretation of the wiper insert geometry in the catalogues of Sandvik Coromant [7, 8], one notes some ambiguities. Thus, Fig. 1 and Fig. 2 present geometric interpretations of wiper insert geometry taken from two different catalogues of Sandvik Coromant.

There is a significant difference between the interpretation presented on Fig. 1 and Fig. 2 regarding the central circle with radius $r_{\epsilon 1}$. Fig. 1 shows the circle and this helps to uniformly define the length of wiper radius b_s . Fig. 2 does not indicate the central circle with radius $r_{\epsilon 1}$ which leaves room for ambiguities when trying to determine the length of the wiper radius b_s . Hence one may conclude that b_s in Fig. 1 can differ from that shown on Fig. 2. The same conclusion arises if we compare the value for b_s in the catalogues [7] and [8] for identical finishing inserts.

This paper aims at developing mathematical models for predicting the maximum height of roughness profile (total height of profile) using wiper insert geometry as a function

of the feed f . This research uses the symbol $Rt(Rz)$ to denote the maximum height of roughness profile.

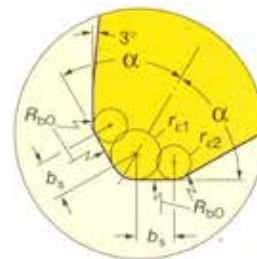


Fig. 1. Wiper insert geometry according to [7]

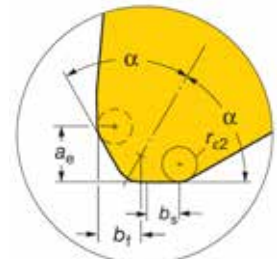


Fig. 2. Wiper insert geometry according to [8]

Mathematical models for the parameter $Rt(Rz)$ as a function of the feed f

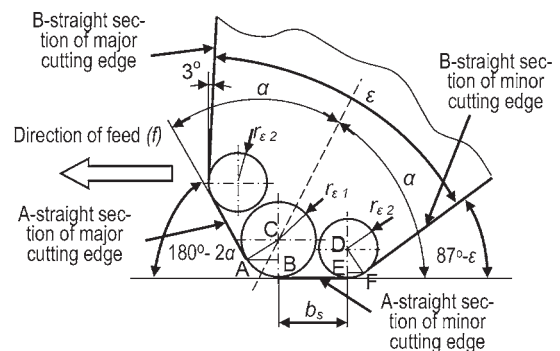


Fig. 3. Wiper insert geometry

This research makes use of the wiper insert geometry graphic interpretation shown on Fig. 3.

Case 1

The feed f (mm/r) less than or equal to length of wiper radius b_s (mm). In the case when $f \leq b_s$, theoretically we get a flat surface, or:

$$Rt(Rz) = 0 \quad (1)$$

Case 2

The feed f (mm/r) greater than the length of wiper radius b_s (mm), but only the radii $r_{\epsilon 1}$ and $r_{\epsilon 2}$ participate in the formation of roughness profile, Fig. 4.

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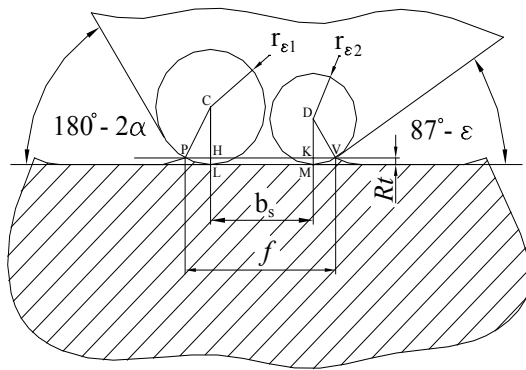


Fig. 4. Geometric interpretation of Case 2 when cutting using wiper insert geometry

$$Rt(Rz) = \frac{(f - b_s)^2}{2(\sqrt{r_{\epsilon 1}} + \sqrt{r_{\epsilon 2}})^2} \quad (2)$$

Case 3

The feed f (mm/r) greater than the length of wiper radius b_s (mm), but the radii $r_{\epsilon 1}$, $r_{\epsilon 2}$ and the B-straight section of the minor cutting edge participates in the formation of the roughness profile, Fig. 5.

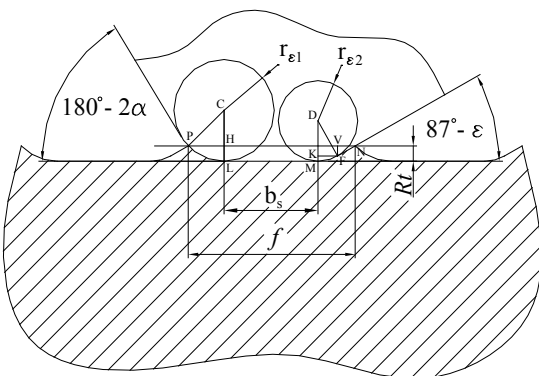


Fig. 5. Geometric interpretation of Case 3 when cutting using wiper insert geometry.

$$Rt(Rz) = \frac{\frac{K}{\operatorname{tg}(87^\circ - \epsilon)} - r_{\epsilon 1} - \sqrt{r_{\epsilon 1}^2 - \frac{2Kr_{\epsilon 1}}{\operatorname{tg}(87^\circ - \epsilon)} - K^2}}{\frac{1}{\operatorname{tg}^2(87^\circ - \epsilon)} + 1} \quad (3)$$

Case 4

The feed f (mm/r) greater than the length of wiper radius b_s (mm), but the radii $r_{\epsilon 1}$, $r_{\epsilon 2}$, the A-straight section of the major cutting edge and the B-straight of the minor cutting edge participate in the formation of the roughness profile, Fig. 5.

Conclusion

The equations for predicting the maximum height of roughness profile when using wiper insert, suggest that the parameter $Rt(Rz)$ depends on a variable number of values ($r_{\epsilon 1}$, $r_{\epsilon 2}$, b_s , ϵ , α) that participate in defining the wiper insert geometry.

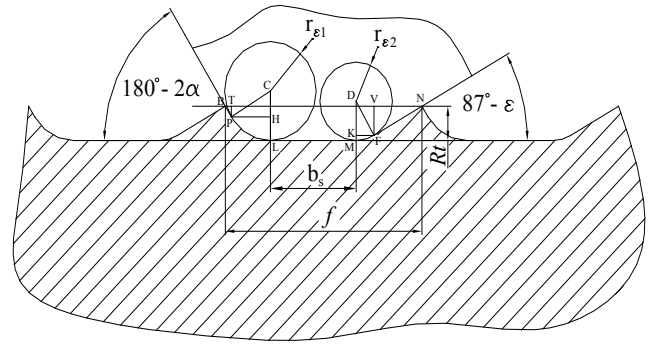


Fig. 6. Geometric interpretation of Case 4 when cutting using wiper insert geometry

$$Rt(Rz) = \frac{f - b_s - r_{\epsilon 1}(\sin(180^\circ - 2\alpha) - \frac{1 - \cos(180^\circ - 2\alpha)}{\operatorname{tg}(180^\circ - 2\alpha)})}{\frac{1}{\operatorname{tg}(180^\circ - 2\alpha)} + \frac{1}{\operatorname{tg}(87^\circ - \epsilon)}} - \frac{r_{\epsilon 2}(\sin(87^\circ - \epsilon) - \frac{1 - \cos(87^\circ - \epsilon)}{\operatorname{tg}(87^\circ - \epsilon)})}{\frac{1}{\operatorname{tg}(180^\circ - 2\alpha)} + \frac{1}{\operatorname{tg}(87^\circ - \epsilon)}} \quad (4)$$

Thus, in Case 2, $Rt(Rz)$ directly depends on the feed f , the length of wiper radius b_s , and the radii $r_{\epsilon 1}$ and $r_{\epsilon 2}$. In addition to the values ($r_{\epsilon 1}$, $r_{\epsilon 2}$, b_s) of Case 2, we also have the angle ϵ in Case 3 and the angle α in Case 4. Case 1 presents an interesting analysis. This usually occurs during finishing. Theoretically, if the feed f is less than b_s then the surface roughness prediction model based on the kinematical-geometrical copying of the cutting tool onto the machined surface loses its significance since it yields an ideally flat surface which cannot happen in practice [2].

The lack of information in the currently available catalogues of Sandvik Coromant about the value of the radius $r_{\epsilon 1}$ represents a deficiency of the experimental verification of the proposed models (1), (2), (3) and (4).

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